

Λύσεις διαγωνίσματος 21/11/2020

ΘΕΜΑ Α $A_1-\gamma$ $A_2-\gamma$ $A_3-\delta$ $A_4-\alpha$ A_5 $\Lambda\Lambda\Xi\Lambda\Xi$

ΘΕΜΑ Β B_1 $B_1-\alpha$ $I_{O\lambda\Delta} = I_{AB} + I_{GO} + I_{S\alpha}$

$$\Rightarrow I_{O\lambda\Delta} = \frac{1}{12} m l^2 + \frac{1}{12} m l^2 + m \frac{l^2}{4} + (m R^2 + m (l+R)^2)$$

$$\Rightarrow I_{O\lambda\Delta} = \frac{1}{6} m l^2 + \frac{1}{4} m l^2 + m \frac{l^2}{4} + \frac{9}{4} m l^2$$

$$\Rightarrow I_{O\lambda\Delta} = \left(\frac{1}{6} + \frac{1}{4} + \frac{10}{4} \right) m l^2 = \frac{2+33}{12} m l^2 \quad l^2 = \frac{35}{12} m l^2$$

$$\Rightarrow \boxed{I_{O\lambda\Delta} = \frac{35}{12} m l^2}$$

Β2 $I-\beta, II-\beta$ I) Χάνει επαφή στη θύμη $A=2\Delta l, y=\Delta l = \frac{A}{2}$
 ΘΙ $K\Delta l = 2mg$

II) ΑΔΕΤ στη θύμη: $v = \omega \sqrt{A^2 - y^2} \Rightarrow v^2 = \frac{k}{2m} A^2 - \frac{A^2}{4} = \frac{k}{2m} \frac{3}{4} A^2$

από ΘΙ $\frac{k}{2m} = \frac{g}{\Delta l} \rightarrow v^2 = \frac{g}{\Delta l} \frac{3}{4} A^2 \Rightarrow v^2 = \frac{3}{4} \frac{g}{A/2} A^2 \Rightarrow v^2 = \frac{3}{2} g A$

ΘΜΚΕ $0 - \frac{1}{2} m v^2 = -mg \cdot h \Rightarrow h = \frac{v^2}{2g} = \frac{\frac{3}{2} g A}{2g} \Rightarrow h = \frac{3}{4} A$

Άρα διανύει $d = A + \Delta l + h = A + \frac{A}{2} + \frac{3}{4} A \Rightarrow d = \frac{9}{4} A \Rightarrow \boxed{d = 2,25 A}$

Β3 $I-\alpha$ $II-\gamma$ $P_2 = P_{atm} + \rho_1 g H = P_{atm} + \rho_1 g \frac{P_{atm}}{10 \rho_1 g} = P_{atm} + \frac{1}{10} P_{atm}$

$\Rightarrow P_2 = 1,1 P_{atm}$ και $A_1 v_1 = A_2 v_2 \Rightarrow v_1 = \frac{v_2}{2} \Rightarrow v_2 = 2v_1$

Bernoulli $P_1 + \frac{1}{2} \rho_1 v_1^2 = P_2 + \frac{1}{2} \rho_2 v_2^2 \Rightarrow 1,6 P_{atm} + \frac{1}{2} \rho_1 v_1^2 = 1,1 P_{atm} + \frac{1}{2} \rho_1 4 v_1^2$

$1,6 P_{atm} - 1,1 P_{atm} = \frac{1}{2} \rho_1 v_1^2 (4-1) \Rightarrow 0,5 P_{atm} = \frac{1}{2} \rho_1 v_1^2 \cdot 3 \Rightarrow v_1^2 = \frac{P_{atm}}{3 \rho_1}$

$\Rightarrow v_1 = \sqrt{\frac{P_{atm}}{3 \rho_1}}$

Αρυστρεα $P_A = P_1 + \rho_1 g h_1$ $S_{\text{είσα}} < \begin{matrix} P_B = P_2 + \rho_1 g h_2 \\ P_r = P_B + \rho_2 g \Delta h \end{matrix} \Rightarrow P_A = P_r$

$\Rightarrow P_1 + \rho_1 g h_1 = P_2 + \rho_1 g h_2 + \rho_2 g \Delta h \Rightarrow P_1 - P_2 = \rho_2 g \Delta h - \rho_1 g (h_1 - h_2)$

$\Rightarrow 1,6 P_{atm} - 1,1 P_{atm} = \rho_2 g \Delta h - \rho_1 g \Delta h$

$\Rightarrow 0,5 P_{atm} = 5 \rho_1 g \Delta h - \rho_1 g \Delta h \Rightarrow \frac{1}{2} P_{atm} = 4 \rho_1 g \Delta h \quad \left(H = \frac{P_{atm}}{10 \rho_1 g} \right)$

$\Rightarrow \frac{1}{2} 10 \rho_1 g H = 4 \rho_1 g \Delta h \Rightarrow \boxed{\Delta h = 1,25 H}$

ΘΕΜΑ Γ

$$H = 5\text{m} \quad U = 5\text{m/s} \quad h = 4\text{m} \quad V = 20\text{m}^3 \quad d = 3,2\text{m} \quad A_1 = 4 \cdot 10^{-3}\text{m}^2 \quad A_2 = 2 \cdot 10^{-3}\text{m}^2$$

$$A = 2 \cdot 10^{-3}\text{m}^3$$

$$\Gamma_1 \text{ α) } \Pi = \frac{V}{t} \Rightarrow A \cdot U = \frac{V}{t} \Rightarrow t = \frac{V}{AU} = \frac{36}{10^{-2}} = 3600 \text{ sec} \Rightarrow \boxed{t = 3600 \text{ sec} = 1\text{h}}$$

$$\text{β) } \Theta \text{ΜΚΕ } \frac{1}{2} \Delta m U^2 - 0 = -\Delta m g H + W_{\text{avr}} \Rightarrow W_{\text{avr}} = \frac{1}{2} \Delta m U^2 + \Delta m g H$$

$$W_{\text{avr}} = \frac{1}{2} \rho \cdot \Delta V \cdot U^2 + \rho \cdot \Delta V \cdot g H \quad \Delta V = V = 36\text{m}^3$$

$$W_{\text{avr}} = \frac{1}{2} 10^3 \cdot 36 \cdot 25 + 10^3 \cdot 36 \cdot 10 \cdot 5 = 450 \cdot 10^3 + 1800 \cdot 10^3 = 2200 \cdot 10^3 \text{ J}$$

$$\boxed{W_{\text{avr}} = 22,5 \cdot 10^5 \text{ J}}$$

$$\delta) P_{\text{avr}} = \frac{W_{\text{avr}}}{\Delta t} = \frac{1}{2} \rho \Pi U^2 + \rho \Pi \cdot g H = \rho \Pi \left(\frac{1}{2} U^2 + g H \right), \quad \underline{\underline{\Pi = AU = 10^{-2} \text{ m}^3/\text{s}}}$$

$$P_{\text{avr}} = 10^3 \cdot 10^{-2} (12,5 + 50) \Rightarrow P_{\text{avr}} = 62,5 \cdot 10 \Rightarrow \boxed{P_{\text{avr}} = 625 \text{ W}}$$

$$\Gamma_2 \quad \Pi = AU = 10^{-2} \text{ m}^3/\text{s} = \Pi_{\text{av}1} \lambda_{1\text{av}}$$

$$U_2 = \sqrt{2g(h-d)} = \sqrt{2 \cdot 10 \cdot 0,8} \Rightarrow U_2 = 4\text{m/s} \quad \Pi_2 = \Pi_{\text{av}2} = A_2 U_2 = 8 \cdot 10^{-3} \text{ m}^3/\text{s}$$

$\Pi_{\text{av}1} > \Pi_{\text{av}2} \rightarrow$ η σταθμη ανεβαίνει

$$\text{Όταν σταθεροποιηθεί } \Pi_{\text{av}1} = \Pi_{\text{av}2} \Rightarrow 10^{-2} = A_2 U_2' \Rightarrow 10^{-2} = 2 \cdot 10^{-3} U_2'$$

$$\Rightarrow U_2' = 5\text{m/s} \rightarrow U_2' = \sqrt{2g(h'-d)} \Rightarrow U_2'^2 = 2g(h'-d) \Rightarrow 25 = 20(h'-d)$$

$$1,25 = h' - 3,2 \Rightarrow \boxed{h' = 4,45\text{m}}$$

$$\Gamma_3 \quad U_2' = 5\text{m/s} \quad X_{\text{max}} = U_2' \cdot t_{\text{ε}5} = 5 \cdot 0,8 \Rightarrow \boxed{X_{\text{max}} = 4\text{m}}$$

$$t_{\text{ε}5} = \sqrt{\frac{2d}{g}} = \sqrt{\frac{2 \cdot 3,2}{10}} = \sqrt{0,64} = 0,8 \text{ sec}$$

$$\Gamma_4 \quad P_1 + \frac{1}{2} \rho U_1'^2 = P_{\text{atm}} + \frac{1}{2} \rho U_2'^2 \quad A_1 U_1' = A_2 U_2' \Rightarrow 25 U_1' = 20 U_2'$$

$$P_1 = P_{\text{atm}} + \frac{1}{2} \rho (U_2'^2 - U_1'^2) \quad U_1' = \frac{4}{5} U_2' = 4\text{m/s}$$

$$P_1 = P_{\text{atm}} + \frac{1}{2} \rho \left(U_2'^2 - \frac{16}{25} U_2'^2 \right) = P_{\text{atm}} + \frac{1}{2} \rho \frac{9}{25} U_2'^2$$

$$P_1 = 100 \cdot 10^3 + \frac{9}{50} \cdot 25 \cdot 10^3 = 100 \cdot 10^3 + 4,5 \cdot 10^3 = 104,5 \cdot 10^3 \text{ N/m}^2$$

$$\boxed{P_1 = 1,045 \cdot 10^5 \text{ N/m}^2}$$

$$P = \frac{W}{\Delta t} = \frac{(P_1 - P_2) \Delta V}{\Delta t} = (P_1 - P_2) \frac{\Pi'}{A_2 U_2'} = (104,5 \cdot 10^3 - 100 \cdot 10^3) 10^{-2} \Rightarrow \boxed{P = 45 \text{ W}}$$

$A_2 U_2' = 10^{-2} \text{ m}^3/\text{s}$

ΘΕΜΑ Δ

$m_1 = 3 \text{ kg}$ $k = 100 \text{ N/m}$ $m_2 = 1 \text{ kg}$

$U_0 = \sqrt{3} \text{ m/s}$ $U_k = 2 \text{ m/s}$

$\Delta 1$ α) $\omega_1 = \sqrt{\frac{k}{m_1}} = \sqrt{\frac{100}{3}} = \frac{10}{\sqrt{3}} = \frac{\sqrt{3}}{3} 10$

$U_{1 \text{ max}} = U_0 = \omega_1 A_1 \Rightarrow \sqrt{3} = \frac{10}{\sqrt{3}} A_1 \Rightarrow A_1 = 0,3 \text{ m}$

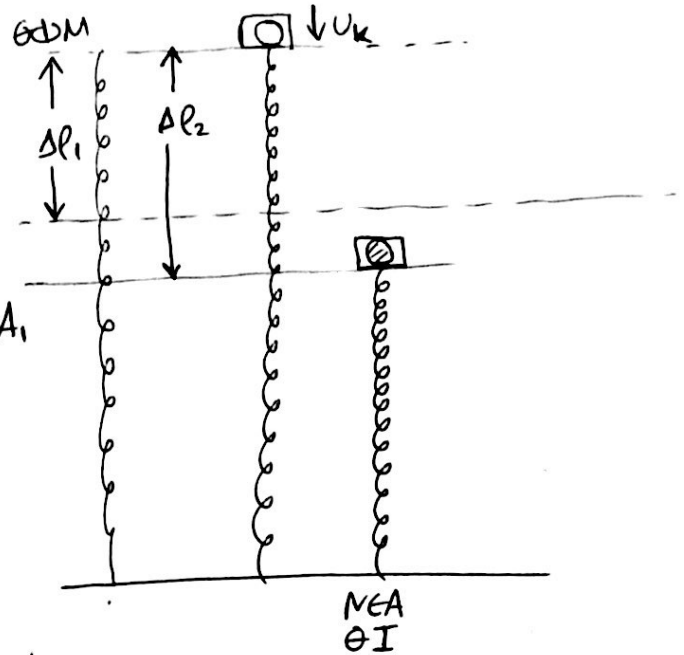
β) $\Theta I m_1$ $k \Delta l_1 = m_1 g \Rightarrow \Delta l_1 = \frac{m_1 g}{k} = 0,3 \text{ m} = A_1$

Άρα η $\Theta \Phi M = \text{ανω αμερεια}$ $U_1 = 0$.

$\Delta \Delta O$ $m_2 U_2 + m_1 U_1^{\rightarrow 0} = m_0 U_k$

$1 \cdot U_2 = 4 \cdot 2\sqrt{3} \Rightarrow U_2 = 8\sqrt{3} \text{ m/s}$

γ) $h_2 = \frac{U_2^2 - U^2}{2g} = \frac{64 \cdot 3 - 36 \cdot 3}{2 \cdot 10} = \frac{3 \cdot 28}{2 \cdot 10} \Rightarrow h_2 = 4,2 \text{ m} \rightarrow h = h_2 + \Delta l_1 = 4,5 \text{ m}$



$\Delta 2$ $NEA \Theta I$ $m_0 g = k \Delta l_2 \Rightarrow \Delta l_2 = \frac{m_0 g}{k} = 0,4 \text{ m}$

$\Delta \Delta E T$ $\frac{1}{2} k A^2 = \frac{1}{2} m_0 U_k^2 + \frac{1}{2} k \Delta l_2^2 \Rightarrow A = \sqrt{\frac{m_0}{k} U_k^2 + \Delta l_2^2} = \sqrt{\frac{4}{100} \cdot 12 + \frac{16}{100}}$

$\Rightarrow A = \sqrt{\frac{64}{100}} \Rightarrow A = 0,8 \text{ m}$

$t=0$ $y = +0,4 \text{ m}$ $U < 0$ $y = + \frac{A}{2}$

$\phi_0 = 5\pi/6$ $\omega = \sqrt{\frac{k}{m_0}} = 5 \text{ rad/s}$

$y = A \sin(\omega t + \phi_0)$

$y = 0,8 \cdot \sin(5t + 5\pi/6) \text{ SI}$

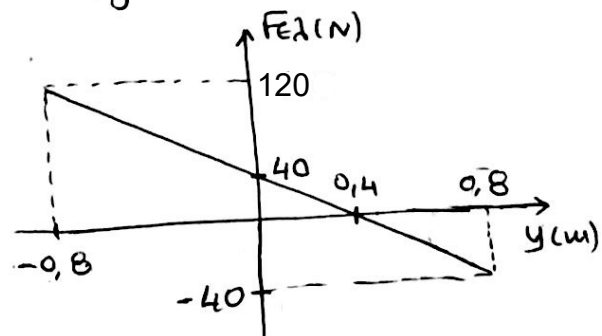
$\Delta 3$ $\Sigma F = m_0 a \Rightarrow F_{ελ} - m_0 g = -m_0 \omega^2 y \Rightarrow F_{ελ} = m_0 g - k \cdot y$

$\Rightarrow F_{ελ} = 40 - 100 \cdot y$ $-0,8 \text{ m} \leq y \leq +0,8 \text{ m}$

$y=0$ $F_{ελ} = 40 \text{ N}$, $y = +0,8 \text{ m} \rightarrow F_{ελ} = -40 \text{ N}$

$y = -0,8 \text{ m} \rightarrow F_{ελ} = 120 \text{ N}$

$y = +0,4 \text{ m} \rightarrow F_{ελ} = 0$



$\Delta 4$ $\frac{dP}{dt} = \Sigma F_1 = m_1 |a| = m_1 \omega^2 |y| \Rightarrow 30 = 3 \cdot 25 |y|$

$\Rightarrow |y| = 0,4 \text{ m} \rightarrow |U| = \omega \sqrt{A^2 - y^2} = 5 \sqrt{\frac{64}{100} - \frac{16}{100}} = \frac{5 \cdot \sqrt{48}}{10} = \frac{4\sqrt{3}}{2} \Rightarrow |U| = 2\sqrt{3} \text{ m/s}$

προς τα ανω = προς τα αρνητικά $U = -2\sqrt{3} \text{ m/s}$ $\left. \begin{array}{l} \text{προς τα ανω} \\ \text{προς τα αρνητικά} \end{array} \right\} \frac{dK}{dt} = \Sigma F U = -k \cdot y \cdot U$

πανω απο ΘI $y = +0,4 \text{ m}$, $U = -2\sqrt{3} \text{ m/s} \rightarrow \frac{dK}{dt} = -100 \cdot (+0,4) \cdot (-2\sqrt{3}) \Rightarrow \frac{dK}{dt} = +80\sqrt{3} \frac{\text{J}}{\text{s}}$

κτω απο ΘI $y = -0,4 \text{ m}$, $U = -2\sqrt{3} \text{ m/s} \rightarrow \frac{dK}{dt} = -100 \cdot (-0,4) \cdot (-2\sqrt{3}) \Rightarrow \frac{dK}{dt} = -80\sqrt{3} \frac{\text{J}}{\text{s}}$