

Λύσεις Σιαγκωνίσταρως 28/2/2021

Θέμα A $A_1 - \alpha, A_2 - \gamma, A_3 - \gamma, A_4 - \gamma, A_5$ ΙΙΙΣΑ

Θέμα B $B_1 - \alpha$

$$\vec{B}_2 + \vec{B}_1 + \vec{B}_2 = \vec{0} \Rightarrow B_2 = B_1 + B_2 \Rightarrow$$

$$\Rightarrow k \mu 4 \pi n I = \frac{2 k \mu I_1}{d} + \frac{2 k \mu I_2}{d} \Rightarrow I = \frac{I_1 + I_2}{2 \pi n d}$$

B2 - β Αρχικά $R_{\lambda} = R + r = R + R/2 \Rightarrow R_{\lambda} = 3R/2$

$$I = \frac{\Sigma}{R_{\lambda}} = \frac{2\Sigma}{3R} \quad | \text{δορυφορία } \sum F_y = 0 \Rightarrow F_L = mg \Rightarrow BI\ell = mg \quad ①$$

$$\delta-\text{κλειστός} \quad R'_{\lambda} = \frac{R \cdot R}{R+R} + r = \frac{R}{2} + \frac{R}{2} \Rightarrow R'_{\lambda} = R$$

$$I' = \frac{\Sigma}{R} , \quad I' = I_{KL} + I_R , \quad V_{KL} = V_R \Rightarrow I_{KL} R = I_R R \Rightarrow I_{KL} = I_R$$

$$I' = 2I_{KL}$$

$$\text{Άρα} \quad I_{KL} = \frac{I'}{2} = \frac{\Sigma}{2R} \rightarrow F'_L = BI_{KL} \cdot \ell$$

$$\frac{I_{KL}}{I} = \frac{\Sigma/2R}{2\Sigma/3R} \Rightarrow \frac{I_{KL}}{I} = \frac{3}{4} \Rightarrow I_{KL} = \frac{3}{4} I$$

$$F'_L = B \frac{3}{4} I \ell = \frac{3}{4} BI\ell \xrightarrow{①} F'_L = \frac{3}{4} mg$$

$$\sum F_y = m\alpha \Rightarrow mg - F'_L = m \cdot \alpha \Rightarrow mg - \frac{3}{4} mg = m\alpha$$

$$\Rightarrow m\alpha = \frac{1}{4} mg \Rightarrow \alpha = g/4 \downarrow$$

B3 - α $\Delta O : \vec{P}_{\text{πριν}} = \vec{P}_{\text{μετά}} \Rightarrow \vec{P}_1 + \vec{P}_2 = \vec{P}_k \downarrow +$

$$P_1 - P_2 = 0 \Rightarrow w_1 v_1 = w_2 v_2 \Rightarrow 4w v_1 = w v_2 \Rightarrow v_2 = 4v$$

$$\frac{E_{\text{σπωλ}}}{K_P} = K_{\text{πριν}} - K_{\text{μετά}} = \frac{1}{2} w_1 v_1^2 + \frac{1}{2} w_2 v_2^2 = \frac{1}{2} 4w v_1^2 + \frac{1}{2} w 16v^2$$

$$\frac{E_{\text{σπωλ}}}{K_P} = 2w v_1^2 + 8w v_1^2 \Rightarrow \frac{E_{\text{σπωλ}}}{K_P} = 10w v_1^2$$

$$\Theta I m_1 : \sum F = 0 \Rightarrow F_{\ell_1} = m_1 g \Rightarrow k \Delta \ell_1 = 4m_1 g \Rightarrow \Delta \ell_1 = \frac{4m_1 g}{k}$$

$$\Theta I m_0 : \sum F = 0 \Rightarrow F_{\ell_2} = m_0 g \Rightarrow k \Delta \ell_2 = 5m_0 g \Rightarrow \Delta \ell_2 = \frac{5m_0 g}{k}$$

$$A_0 = \Delta \ell_2 - \Delta \ell_1 = \frac{5m_0 g}{k} - \frac{4m_1 g}{k} \Rightarrow A_0 = \frac{m g}{k}$$

$$A = A_0 e^{-\lambda t} \quad \lambda t = \lambda \frac{2 \ln 2}{1} = 2 \ln 2 = \ln 2^2 = \ln 4$$

$$A = A_0 e^{-\ln 4} = \frac{A_0}{e^{\ln 4}} \Rightarrow A = \frac{A_0}{4}$$

$$E_{\text{kinetic}} = E_0 - E \quad \text{or} \quad E_0 = \frac{1}{2} D A_0^2, \quad E = \frac{1}{2} D A^2 = \frac{1}{16} \frac{1}{2} D A_0^2$$

$$E_{\text{kinetic}} = \frac{1}{2} D A_0^2 - \frac{1}{16} \frac{1}{2} D A_0^2 = \frac{15}{32} D A_0^2$$

$$T_0 = T \rightarrow \omega_0 = \omega \rightarrow D = K \quad E_{\text{kinetic}} = \frac{15}{32} K A_0^2$$

$$\text{Ist } E_{\text{kinetic}} = \frac{1}{4} E_{\text{kinetic}} \Rightarrow \frac{15}{32} K A_0^2 = \frac{1}{4} 10 m v_1^2$$

$$\Rightarrow \frac{3}{16} K A_0^2 = m v_1^2 \Rightarrow v_1^2 = \frac{3}{16} \frac{K A_0^2}{m} \Rightarrow v_1^2 = \frac{3}{16} \frac{K}{m} \frac{m g^2}{K^2}$$

$$\Rightarrow v_1^2 = \frac{3}{16} \frac{m g^2}{K} \Rightarrow \boxed{v_1 = \frac{3}{4} \sqrt{\frac{m g^2}{K}}}$$

Θ_{EMA}

$$A_1 = \sqrt{3} A, \quad A_2 = A \quad \varphi_{02} = \pi/2 \quad \Delta \varphi = \pi/2$$

$$\boxed{r_1} \quad \text{Ist: } x_0 = x_1 + x_2 \Rightarrow x_0 = \sqrt{3} A \sin(\omega t) + A \sin\left(\omega t + \frac{\pi}{2}\right)$$

$$t = T/6 \quad x_0 = \sqrt{3} A \sin\left(\frac{2\pi}{T} \frac{T}{6}\right) + A \sin\left(\frac{2\pi}{T} \frac{T}{6} + \frac{\pi}{2}\right)$$

$$\Rightarrow +0,4m = \sqrt{3} A \sin \frac{\pi}{3} + A \sin \frac{5\pi}{6}$$

$$\Rightarrow +0,4m = \sqrt{3} A \frac{\sqrt{3}}{2} + A \frac{1}{2} \Rightarrow 2A = 0,4 \Rightarrow \boxed{A = 0,2m}$$

$$\Delta t = \frac{T}{2} \Rightarrow \frac{1}{100} = \frac{T}{2} \Rightarrow T = \frac{1}{50} \text{ sec}, \quad \omega = \frac{2\pi}{T} = 100\pi \frac{\text{rad}}{\text{sec}}$$

$$\Gamma_2 \quad A_{0j} = \sqrt{A_1^2 + A_2^2 + 2A_1 A_2 \sin \varphi} = \sqrt{3A^2 + A^2} = 2A$$

$$A_{0j} = 0,4 \text{ m} \quad E \varphi \varphi_0 = \frac{A_2 \sin \varphi}{A_1 + A_2 \sin \varphi} = \frac{A}{A\sqrt{3}} = \frac{\sqrt{3}}{3} \rightarrow \varphi_0 = \frac{\pi}{6}$$

$$x_{0j} = A_{0j} \sin(\omega t + \varphi_0) \Rightarrow x_{0j} = 0,4 \cdot \sin\left(100\pi t + \frac{\pi}{6}\right) \text{ SI}$$

$$\Gamma_3 \quad x_1 = -x_2 \quad \stackrel{2}{=} \varphi_{0pa} \Rightarrow x_{0j} = 0 \quad \mu \in U > 0$$

$$A_{0pa} \quad U = U_{\max} = \omega A_{0j} = 100\pi \cdot 0,4 \Rightarrow U = U_{\max} = 40\pi \frac{\text{m}}{\text{s}}$$

$$\Gamma_4 \quad \omega_1 = \omega = 100\pi \frac{\text{rad}}{\text{s}} \quad \omega_2 = \omega + \frac{4}{100}\omega = \frac{104}{100}\omega \Rightarrow \omega_2 = 104\pi \frac{\text{rad}}{\text{s}}$$

$$x'_{0j} = 2A \sin\left(\frac{\omega_1 - \omega_2}{2}t\right) \sin\left(\frac{\omega_1 + \omega_2}{2}t\right) = 0,4 \cdot \sin(-2t) \cdot \sin(102t)$$

$$x_{0j} = 0,4 \cdot \sin(2\pi t) \sin(102\pi t) \text{ SI}$$

$$\Gamma_5 \quad U_1 = U_{1\max} \sin(\omega_1 t) = \omega_1 A \sin(\omega_1 t) \Rightarrow U_1 = 20\pi \sin(100\pi t) \text{ SI}$$

$$U_2 = U_{2\max} \sin(\omega_2 t) = \omega_2 A \sin(\omega_2 t) \Rightarrow U_2 = 20,8\pi \sin(104\pi t) \text{ SI}$$

$$T_S = \frac{2\pi}{|\omega_1 - \omega_2|} = \frac{2\pi}{4\pi} \Rightarrow T_S = \frac{1}{2} \text{ sec.} \quad \rightarrow t = T_S/4 = \frac{1}{8} \text{ sec}$$

$$U = U_1 + U_2 = 20 \sin\left(100\frac{\pi}{8}t\right) + 20,8 \sin\left(104\frac{\pi}{8}t\right)$$

$$U = 20\pi \sin(12,5\pi) + 20,8\pi \sin(13\pi)$$

$$U = 20\pi \sin(12\pi + \pi/2) + 20,8\pi \sin(12\pi + \pi) = 20\pi \cancel{\sin \frac{\pi}{2}} + 20,8\pi \cancel{\sin \pi}$$

$$U = -20,8\pi \frac{\text{m}}{\text{s}}$$

ΘΕΜΑ Δ

A1 ΘΜΚΕ για υ₁: $k_{1\text{τελ}} - k_{1\text{αρχ}} = W_{m_1 g} \Rightarrow \frac{1}{2} m_1 v_1^2 - \frac{1}{2} m_1 v_0^2 = m_1 g l$

$$\Rightarrow v_1^2 = v_0^2 + 2gl = 64 \Rightarrow v_1 = 8 \text{ m/s.}$$

A10: $\vec{P}_{\text{ηρν}} = \vec{P}_{\text{μετα}} \Rightarrow \vec{P}_1 = \vec{P}'_1 + \vec{P}_2 \Rightarrow m_1 v_1 = 0 + m_2 v_2 \Rightarrow$

$$\Rightarrow v_2 = \frac{m_1 v_1}{m_2} \Rightarrow v_2 = \frac{16}{3} \text{ m/s.}$$

$$\left. \begin{array}{l} K_{\text{ηρν}} = \frac{1}{2} m_1 v_1^2 = 16 \text{ J} \\ K_{\text{μετα}} = \frac{1}{2} m_2 v_2^2 = \frac{32}{3} \text{ J} \end{array} \right\} E_{\text{απωλ}} = K_{\text{ηρν}} - K_{\text{μετα}} = \frac{16}{3} \text{ J}$$

$$\Pi_1 = \frac{E_{\text{απωλ}}}{K_{\text{ηρν}}} 100\% \Rightarrow \boxed{\Pi_1 = \frac{100}{3}\% = 33,33\%}$$

A2 $v'_2 = \frac{m_2 - m_3}{m_2 + m_3} v_2 \Rightarrow v'_2 = -\frac{4}{3} \text{ m/s}$, $v'_3 = \frac{2m_2}{m_2 + m_3} v_2 \Rightarrow v'_3 = \frac{4}{5} \text{ m/s}$

A3 $\Pi_2 = \frac{\Delta K_2}{k_2} 100\% = \frac{k'_2 - k_2}{k_2} 100\% = \left(\frac{1/2 m_2 v'_2^2}{1/2 m_2 v_2^2} - 1 \right) 100\%$

$$\Pi_2 = \left[\left(\frac{v'_2}{v_2} \right)^2 - 1 \right] 100\% = \left(\frac{1}{16} - 1 \right) 100\% = -\frac{15}{16} 100\% \Rightarrow \boxed{\Pi_2 = -93,75\%}$$

A4 ΘΜΚΕ για Σ_3 : $k_{3\text{τελ}} - k_{3\text{αρχ}} = W_{T_3} + W_{F_{\text{ελ}}}$

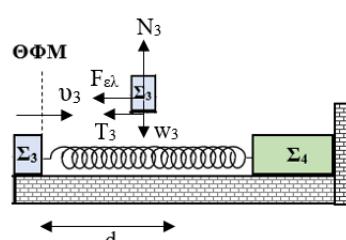
$$0 - \frac{1}{2} m_3 v_3^2 = -T_3 \cdot d - \frac{1}{2} k d^2$$

$$\text{οπου } T_3 = \mu N_3 = \mu m_3 g = S N$$

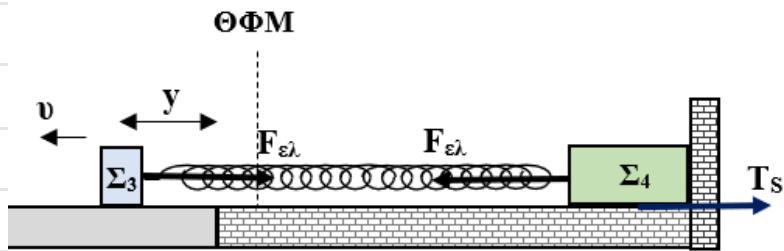
$$-\frac{1}{2} \frac{5}{4} \cdot 16 = -5d - 50d^2 \Rightarrow$$

$$10d^2 + d - 2 = 0$$

$$\Delta = 81 \rightarrow \sqrt{\Delta} = 9 \quad d = \frac{-1 \pm 9}{20} < \boxed{d = 0,4 \text{ m}} \quad d = -0,5 \text{ m} \text{ απορ.}$$



ΔS Η ολιγότερη των Σ_4 αρχίζει σαν $F_{\lambda} \geq T_{\text{max}}$



$$F_{\lambda} \geq T_{\text{max}} \Rightarrow k_y \geq \mu_s N_4 \Rightarrow k_y \geq \mu_s m_4 g \Rightarrow y \geq \frac{\mu_s m_4 g}{k}$$

$$\Rightarrow y \geq \frac{0,4 \cdot 2,5 \sqrt{2} \cdot 10}{100} \Rightarrow y \geq \frac{\sqrt{2}}{10} m \rightarrow y = 0,1\sqrt{2} m$$

Στο τελείωμα $\frac{dP}{dt} = \sum F_x = F_{\lambda} = k_y \Rightarrow \boxed{\frac{dP}{dt} = 10\sqrt{2} N \rightarrow}$

ΘΜΚΕ για m_3 : $K_{\lambda}(y) - K_{\text{ex}}^{\text{θμ}} = W_{T_3} + W_{F_{\lambda}}$

$$\frac{1}{2} m_3 v^2 - \frac{1}{2} m_3 v_3'^2 = -T_3 \cdot 2d + \cancel{V_{\lambda}^{\text{θμ}}} - \cancel{V_{\lambda}(y)}$$

$$\frac{1}{2} m_3 v^2 - \frac{1}{2} m_3 v_3'^2 = -T_3 \cdot 2d - \frac{1}{2} k y^2$$

$$\frac{1}{2} \frac{5}{4} v^2 - \frac{1}{2} \frac{5}{4} \cdot 16 = -5 \cdot 0,8 - \frac{1}{2} \frac{100}{100} \frac{2}{100}$$

$$\frac{5}{8} v^2 = 10 - 4 - 1 \Rightarrow v^2 = 8 \Rightarrow \boxed{v = \sqrt{8} m/s = 2\sqrt{2} m/s}$$